

Step 1

Click SETTINGS.

The screenshot shows the main control interface of the RG3. On the left, there are buttons for 'UNLOAD', 'MOVE TO LOW LIMIT', and 'MOVE TO HIGH LIMIT'. The center features a grid of yellow buttons with numbers 0-9 and various fractional values. On the right, a vertical menu contains 'STOP MODE', 'PUSHER MODE', 'AUTOLIST', and 'SETTINGS'. A red arrow points from the 'SETTINGS' button to the 'Remote Serial' tab in the settings menu. Below the main interface, there are buttons for 'HOME', 'MOVE TO LOW LIMIT', 'MOVE TO HIGH LIMIT', 'Reset Fault', and 'Reset Encoder'. A 'Break-In' dialog box is also visible, showing a 'Break in Time (mins)' set to 5 and a 'Do Break In' button.

Step 2

Enter password 5239 and click the REMOTE SERIAL TAB.

Step 3

If you do not have Tool Safe, click REMOTE SERIAL ENABLED. If you have the Tool Safe Option, click REMOTE SERIAL – HAVE IO

Step 4

Select the COM port on which your application will communicate.

The screenshot shows the 'Remote Serial' settings screen. At the top, there is a 'SAVE CHANGES' button and a note: 'Program will restart after Save Changes'. Below this are tabs for 'Password', 'Position', 'Motion', 'IO', 'Remote Serial', 'Tools', and 'FAULTS'. The 'Remote Serial' tab is active. It contains two checkboxes: 'Remote Serial Enabled' and 'Remote Serial - Have IO'. Below these is a field for 'Remote Serial COM Port Name:' with 'COM4' entered. At the bottom, there is a section titled 'Serial Ports Found (Click to Select)' with a list of ports: COM1, COM3, COM4, CNCA0, CNCB0, COM5, COM7, and COM8. A red arrow points from the 'Remote Serial Enabled' checkbox to the 'Remote Serial' tab in the previous screenshot.